LocSense

OEM Module



Features

- 12 parallel channel GPS receiver
- 4000 simultaneous time-frequency search bins
- Better than -135dBm sensitivity
- < 10 second hot start</p>
- < 45 second cold start
- 5m CEP accuracy

LS-40SM

12 Channel GPS Sensor Module

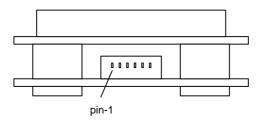
The LS-40SM is an all-in-one GPS receiver module specifically designed for handheld device market. It features small size, low power consumption, and ease of use.

The LS-40SM is optimized for good performance and low cost. Its 12 parallel channels and 4000 time/frequency search bins provide very fast signal lock-on and rapid time to first fix. Having much faster satellite signal acquisition and re-acquisition speed than the conventional 48 correlator design, the LS-40SM offers good navigation performance even in difficult environments.

Both LVTTL-level and RS232-level serial interface are provided on the interface connector.

TECHNICAL SPECIFICATIONS

Receiver Type	12 parallel channel, L1 C/A code
Accuracy	Position 5m CEP Velocity 0.1m/sec
Startup Time	< 10sec hot start < 35sec warm start < 45sec cold start
Reacquisition	1s
Acquisition Sensitivity	Better than -135dBm
Update Rate	1Hz
Dynamics	4G (39.2m/sec ²)
Operational Limits	Altitude < 18,000m or velocity < 515m/s (COCOM limit, either may be exceeded but not both)
Serial Interface	LVTTL level and RS-232 level
Protocol	NMEA-0183 V3.01 GPGGA, GPGLL, GPGSA, GPGSV, GPRMC, GPVTG, GPZDA 4800 baud, 8, N, 1
Datum	Default WGS-84 User definable
Interface Connector	One 1.0mm pitch WTB S/R wafer 87213 SMT R/A type connector
Input Voltage	3.8V ~ 8.0V
Current Consumption	90 ~ 110mA
Dimension	46mm L x 31mm W x 14.5mm H
Weight:	14g
Operating Temperature	-40°C ~ +85°C
Humidity	5% ~ 95%



LS-40SM Lateral View

PINOUT DESCRIPTION

Pin Number	Signal Name	Description
1	Serial Data Out 1	Asynchronous serial output at LVTTL level, to output NMEA message
2	Serial Data In 1	Asynchronous serial input at LVTTL level, to input command message
3	Serial Data Out 2	Asynchronous serial output at RS-232 level, to output NMEA message
4	Serial Data In 2	Asynchronous serial input at RS-232 level, to input command message
5	Power	3.8V ~ 8.0V DC input
6	Ground	Power and signal ground

NMEA Messages

The serial interface protocol is based on the National Marine Electronics Association's NMEA 0183 ASCII interface specification. This standard is fully define in "NMEA 0183, Version 3.01" The standard may be obtained from NMEA, www.nmea.org

GGA - GPS FIX DATA

Time, position and position-fix related data (number of satellites in use, HDOP, etc.).

Format:

\$GPGGA,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,M,<10>,M,<11>,<12>,*<13><CR><LF>

Example:

\$GPGGA,104549.04,2447.2038,N,12100.4990,E,1,06,01.7,00078.8,M,0016.3,M,,*5C<CR><LF>

Field	Example	Description
1	104549.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	2447.2038	Latitude in ddmm.mmmm format
		Leading zeros transmitted
3	N	Latitude hemisphere indicator, 'N' = North, 'S' = South
4	12100.4990	Longitude in dddmm.mmmm format
		Leading zeros transmitted
5	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
6	1	Position fix quality indicator
		0: position fix unavailable
		1: valid position fix, SPS mode
		2: valid position fix, differential GPS mode
7	06	Number of satellites in use, 00 ~ 12
8	01.7	Horizontal dilution of precision, 00.0 ~ 99.9
9	00078.8	Antenna height above/below mean sea level, -9999.9 ~ 17999.9
10	0016.3	Geoidal height, -999.9 ~ 9999.9
11		Age of DGPS data since last valid RTCM transmission in xxx format (seconds)
		NULL when DGPS not used
12		Differential reference station ID, 0000 ~ 1023
		NULL when DGPS not used
13	5C	Checksum

Note: The checksum field starts with a '*' and consists of 2 characters representing a hex number. The checksum is the exclusive OR of all characters between '\$' and '*'.

GLL - LATITUDE AND LONGITUDE, WITH TIME OF POSITION FIX AND STATUS

Latitude and longitude of current position, time, and status.

Format:

\$GPGLL,<1>,<2>,<3>,<4>,<5>,<6>,<7>*<8><CR><LF>

Example:

\$GPGLL,2447.2073,N,12100.5022,E,104548.04,A,A*65<CR><LF>

Field	Example	Description
1	2447.2073	Latitude in ddmm.mmmm format
		Leading zeros transmitted
2	Ν	Latitude hemisphere indicator, 'N' = North, 'S' = South
3	12100.5022	Longitude in dddmm.mmmm format
		Leading zeros transmitted
4	Е	Longitude hemisphere indicator, 'E' = East, 'W' = West
5	104548.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
6	А	Status, 'A' = valid position, 'V' = navigation receiver warning
7	А	Mode indicator
		'N' = Data invalid
		'A' = Autonomous
		'D' = Differential
		'E' = Estimated
8	65	Checksum

GSA - GPS DOP AND ACTIVE SATELLITES

GPS receiver operating mode, satellites used for navigation, and DOP values.

Format:

Example:

\$GPGSA,A,3,26,21,,,09,17,,,,,,10.8,02.1,10.6*07<CR><LF>

Field	Example	Description
1	A	Mode, 'M' = Manual, 'A' = Automatic
2	3	Fix type, 1 = not available, 2 = 2D fix, 3 = 3D fix
3	26,21,,,09,17,,,,,	PRN number, 01 to 32, of satellite used in solution, up to 12 transmitted
4	10.8	Position dilution of precision, 00.0 to 99.9
5	02.1	Horizontal dilution of precision, 00.0 to 99.9
6	10.6	Vertical dilution of precision, 00.0 to 99.9
7	07	Checksum

GSV - GPS SATELLITE IN VIEW

Number of satellites in view, PRN number, elevation angle, azimuth angle, and C/No. Only up to four satellite details are transmitted per message. Additional satellite in view information is sent in subsequent GSV messages.

Format:

\$GPGSV,<1>,<2>,<3>,<4>,<5>,<6>,<7>,...,<4>,<5>,<6>,<7> *<8><CR><LF>

Example:

\$GPGSV,2,1,08,26,50,016,40,09,50,173,39,21,43,316,38,17,41,144,42*7C<CR><LF> \$GPGSV,2,2,08,29,38,029,37,10,27,082,32,18,22,309,24,24,09,145,*7B<CR><LF>

Field	Example	Description
1	2	Total number of GSV messages to be transmitted
2	1	Number of current GSV message
3	08	Total number of satellites in view, 00 ~ 12
4	26	Satellite PRN number, GPS: 01 ~ 32, SBAS: 33 ~ 64 (33 = PRN120)
5	50	Satellite elevation number, 00 ~ 90 degrees
6	016	Satellite azimuth angle, 000 ~ 359 degrees
7	40	C/No, 00 ~ 99 dB
		Null when not tracking
8	7C	Checksum

RMC - RECOMMANDED MINIMUM SPECIFIC GPS/TRANSIT DATA

Time, date, position, course and speed data.

Format:

\$GPRMC,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,<10>,<11>,<12>*<13><CR><LF>

Example:

\$GPRMC,104549.04,A,2447.2038,N,12100.4990,E,016.0,221.0,250304,003.3,W,A*22<CR><LF>

Field	Example	Description
1	104549.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	A	Status, 'V' = navigation receiver warning, 'A' = valid position
3	2447.2038	Latitude in dddmm.mmmm format
		Leading zeros transmitted
4	N	Latitude hemisphere indicator, 'N' = North, 'S' = South
5	12100.4990	Longitude in dddmm.mmmm format
		Leading zeros transmitted
6	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
7	016.0	Speed over ground, 000.0 ~ 999.9 knots
8	221.0	Course over ground, 000.0 ~ 359.9 degrees
9	250304	UTC date of position fix, ddmmyy format
10	003.3	Magnetic variation, 000.0 ~ 180.0 degrees
11	W	Magnetic variation direction, 'E' = East, 'W' = West
12	A	Mode indicator
		'N' = Data invalid
		'A' = Autonomous
		'D' = Differential
		'E' = Estimated
13	22	Checksum

VTG - COURSE OVER GROUND AND GROUND SPEED

Velocity is given as course over ground (COG) and speed over ground (SOG).

Format:

 $GPVTG,<1>,T,<2>,M,<3>,N,<4>,K,<5>^*<6><CR><LF>$

Example:

\$GPVTG,221.0,T,224.3,M,016.0,N,0029.6,K,A*1F<CR><LF>

Field	Example	Description
1	221.0	True course over ground, 000.0 ~ 359.9 degrees
2	224.3	Magnetic course over ground, 000.0 ~ 359.9 degrees
3	016.0	Speed over ground, 000.0 ~ 999.9 knots
4	0029.6	Speed over ground, 0000.0 ~ 1800.0 kilometers per hour
5	А	Mode indicator
		'N' = Data invalid
		'A' = Autonomous
		'D' = Differential
		'E' = Estimated
6	1F	Checksum

ZDA TIME AND DATE

Format: \$GPZDA,<1>,<2>,<3>,<4>,<5>,<6>*<7><CR><LF>

Example:

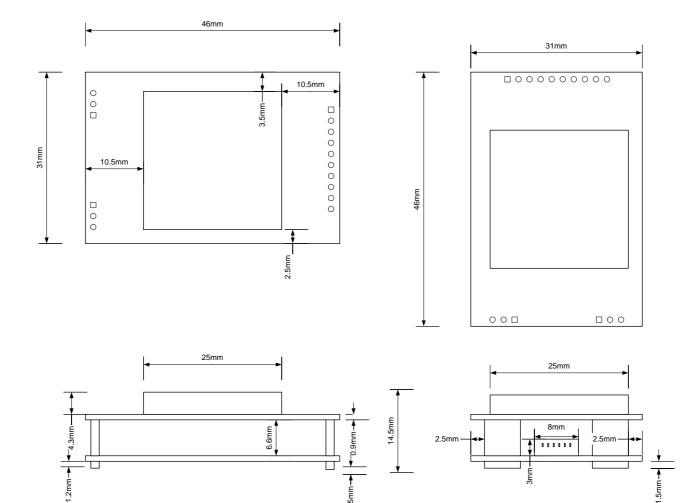
\$GPZDA,104548.04,25,03,2004,,*6C<CR><LF>

Field	Example	Description
1	104548.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	25	UTC time: day (01 31)
3	03	UTC time: month (01 12)
4	2004	UTC time: year (4 digit year)
5		Local zone hour
		Not being output by the receiver (NULL)
6		Local zone minutes
		Not being output by the receiver (NULL)
7	6C	Checksum

Binary Messages

See Binary Message Protocol User's Guide for detailed descriptions.

MECHANICAL CHARACTERISTICS



1.5mm-

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